

2007-2008

JAWAHARLAL NEHRU TECHNOLOGICAL UNIVERSITY
KUKATPALLY, HYDERABAD

B.TECH ELECTRICAL AND ELECTRONICS ENGINEERING

IV year – II Semester

Course Structure

CODE	SUBJECT	T	P	C
	Utilization of Electrical Energy	4+1*	-	4
	ELECTIVE – III	4+1*	-	4
	Advanced Control Systems			
	Digital Control Systems			
	Optimization Techniques			
	ELECTIVE – IV	4+1*	-	4
	Programmable Logic Controllers			
	Object oriented programming			
	Database Management Systems			
	Seminar	-	-	2
	Industry Oriented Mini Project	-	-	2
	Comprehensive Viva	-	-	2
	Project Work	-	-	10
	Total	15	-	28

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4+1*	0	4

UTILIZATION OF ELECTRICAL ENERGY

Objective :

This subject deals with the fundamentals of illumination and its classification and the electric heating and welding. It gives the detailed study of all varieties of Electric drives and their application to electrical traction systems.

UNIT – I ELECTRIC DRIVES

Type of electric drives, choice of motor, starting and running characteristics, speed control, temperature rise, particular applications of electric drives, types of industrial loads, continuous, intermittent and variable loads, load qualification.

UNIT – II ELECTRIC HEATING

Advantages and methods of electric heating, resistance heating induction heating and dielectric heating.

UNIT – III ELECTRIC WELDING

Electric welding, resistance and arc welding, electric welding equipment, comparison between A.C. and D.C. Welding.

UNIT – IV ILLUMINATION FUNDAMENTALS

Introduction, terms used in illumination, laws of illumination, polar curves, photometry, integrating sphere, sources of light.

UNIT – V VARIOUS ILLUMINATION METHODS

Discharge lamps, MV and SV lamps – comparison between tungsten filament lamps and fluorescent tubes, Basic principles of light control, Types and design of lighting and flood lighting.

UNIT – VI ELECTRIC TRACTION – I

System of electric traction and track electrification. Review of existing electric traction systems in India. Special features of traction motor, methods of electric braking-plugging rheostatic braking and regenerative braking.

UNIT – VII ELECTRIC TRACTION – II

Mechanics of train movement. Speed-time curves for different services – trapezoidal and quadrilateral speed time curves.

UNIT – VIII ELECTRIC TRACTION-III

Calculations of tractive effort, power, specific energy consumption for given run, effect of varying acceleration and braking retardation, adhesive weight and braking retardation adhesive weight and coefficient of adhesion.

TEXT BOOK:

1. Utilisation of Electric Energy – by E. Openshaw Taylor, Orient Longman.
2. Art & Science of Utilization of electrical Energy – by Partab, Dhanpat Rai & Sons.

REFERENCE BOOKS:

1. Utilization of Electrical Power including Electric drives and Electric traction – by N.V.Suryanarayana, New Age International (P) Limited, Publishers, 1996.
2. Generation, Distribution and Utilization of electrical Energy – by C.L. Wadhwa, New Age International (P) Limited, Publishers, 1997.

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**ADVANCED CONTROL SYSTEMS
(ELECTIVE – III)**

Objective :

This subject deals with state space, describing function, phase plane and stability analysis including controllability and observability. It also deals with modern control and optimal control systems.

UNIT – I STATE SPACE ANALYSIS

State Space Representation, Solution of State Equation, State Transition Matrix, Canonical Forms – Controllable Canonical Form, Observable Canonical Form, Jordan Canonical Form.

UNIT – II CONTROLLABILITY AND OBSERVABILITY

Tests for controllability and observability for continuous time systems – Time varying case, minimum energy control, time invariant case, Principle of Duality, Controllability and observability form Jordan canonical form and other canonical forms.

UNIT – III DESCRIBING FUNCTION ANALYSIS

Introduction to nonlinear systems, Types of nonlinearities, describing functions, describing function analysis of nonlinear control systems.

UNIT-IV PHASE-PLANE ANALYSIS

Introduction to phase-plane analysis, Method of Isoclines for Constructing Trajectories, singular points, phase-plane analysis of nonlinear control systems.

UNIT-V STABILITY ANALYSIS

Stability in the sense of Lyapunov., Lyapunov's stability and Lypanov's instability theorems. Direct method of Lypanov for the Linear and Nonlinear continuous time autonomous systems.

UNIT – VI MODAL CONTROL

Effect of state feedback on controllability and observability, Design of State Feedback Control through Pole placement. Full order observer and reduced order observer.

UNIT-VII CALCULUS OF VARIATIONS

Minimization of functionals of single function, Constrained minimization. Minimum principle. Control variable inequality constraints. Control and state variable inequality constraints. Euler Lagrangine Equation.

UNIT –VIII OPTIMAL CONTROL

Formulation of optimal control problem. Minimum time, Minimum energy, minimum fuel problems. State regulator problem. Output regulator problem. Tracking problem, Continuous-Time Linear Regulators.

TEXT BOOKS:

1. Modern Control System Theory – by M. Gopal, New Age International Publishers, 2nd edition, 1996

REFERENCE BOOKS:

1. Modern Control Engineering – by K. Ogata, Prentice Hall of India, 3rd edition, 1998
2. Control Systems Engineering by I.J. Nagarath and M.Gopal, New Age International (P) Ltd.
3. Digital Control and State Variable Methods – by M. Gopal, Tata Mc Graw-Hill Companies, 1997.
4. Systems and Control by Stainslaw H. Zak , Oxford Press, 2003.

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DIGITAL CONTROL SYSTEMS
(ELECTIVE-III)

UNIT – I SAMPLING AND RECONSTRUCTION

Introduction, Examples of Data control systems – Digital to Analog conversion and Analog to Digital conversion, sample and hold operations.

UNIT-II THE Z – TRANSFORMS

Introduction, Linear difference equations, pulse response, Z – transforms, Theorems of Z – Transforms, the inverse Z – transforms, Modified Z- Transforms

UNIT-III Z-PLANE ANALYSIS OF DISCRETE-TIME CONTROL SYSTEM

Z-Transform method for solving difference equations; Pulse transforms function, block diagram analysis of sampled – data systems, mapping between s-plane and z-plane.

UNIT – IV STATE SPACE ANALYSIS

State Space Representation of discrete time systems, Pulse Transfer Function Matrix solving discrete time state space equations, State transition matrix and it's Properties, Methods for Computation of State Transition Matrix, Discretization of continuous time state – space equations

UNIT – V CONTROLLABILITY AND OBSERVABILITY

Concepts of Controllability and Observability, Tests for controllability and Observability. Duality between Controllability and Observability, Controllability and Observability conditions for Pulse Transfer Function

UNIT – VI STABILITY ANALYSIS

Mapping between the S-Plane and the Z-Plane – Primary strips and Complementary Strips – Constant frequency loci, Constant damping ratio loci, Stability Analysis of closed loop systems in the Z-Plane. Jury stability test – Stability Analysis by use of the Bilinear Transformation and Routh Stability criterion.

UNIT – VII DESIGN OF DISCRETE TIME CONTROL SYSTEM BY CONVENTIONAL METHODS

Transient and steady – State response Analysis – Design based on the frequency response method – Bilinear Transformation and Design procedure in the w-plane, Lead, Lag and Lead-Lag compensators and digital PID controllers.

UNIT – VIII STATE FEEDBACK CONTROLLERS AND OBSERVERS

Design of state feedback controller through pole placement – Necessary and sufficient conditions, Ackerman's formula.
State Observers – Full order and Reduced order observers.

TEXT BOOKS:

1. Discrete-Time Control systems - K. Ogata, Pearson Education/PHI, 2nd Edition

REFERENCE BOOKS:

1. Digital Control Systems, Kuo, Oxford University Press, 2nd Edition, 2003.
2. Digital Control and State Variable Methods by M.Gopal, TMH

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OPTIMIZATION TECHNIQUES
(ELECTIVE-III)

UNIT – I Introduction and Classical Optimization Techniques:

Statement of an Optimization problem – design vector – design constraints – constraint surface – objective function – objective function surfaces – classification of Optimization problems.

UNIT – II Classical Optimization Techniques

Single variable Optimization – multi variable Optimization without constraints – necessary and sufficient conditions for minimum/maximum – multivariable Optimization with equality constraints.

Solution by method of Lagrange multipliers – multivariable Optimization with inequality constraints – Kuhn – Tucker conditions.

UNIT – III Linear Programming

Standard form of a linear programming problem – geometry of linear programming problems – definitions and theorems – solution of a system of linear simultaneous equations – pivotal reduction of a general system of equations – motivation to the simplex method – simplex algorithm.

UNIT – IV Transportation Problem

Finding initial basic feasible solution by north – west corner rule, least cost method and Vogel's approximation method – testing for optimality of balanced transportation problems.

UNIT – V Unconstrained Nonlinear Programming:

One – dimensional minimization methods: Classification, Fibonacci method and Quadratic interpolation method

UNIT – VI Unconstrained Optimization Techniques

Univariate method, Powell's method and steepest descent method.

UNIT – VII Constrained Nonlinear Programming:

Characteristics of a constrained problem, Classification, Basic approach of Penalty Function method; Basic approaches of Interior and Exterior penalty function methods. Introduction to convex Programming Problem.

UNIT – VIII Dynamic Programming:

Dynamic programming multistage decision processes – types – concept of sub optimization and the principle of optimality – computational procedure in dynamic programming – examples illustrating the calculus method of solution - examples illustrating the tabular method of solution.

TEXT BOOKS:

1. "Engineering optimization: Theory and practice"-by S. S.Rao, New Age International (P) Limited, 3rd edition, 1998.
2. "Introductory Operations Research" by H.S. Kasene & K.D. Kumar, Springer(India), Pvt .LTd.

REFERENCE BOOKS:

- 1 " Optimization Methods in Operations Research and systems Analysis" – by K.V. Mital and C. Mohan, New Age International (P) Limited, Publishers, 3rd edition, 1996.
2. Operations Research – by Dr. S.D.Sharma.
3. "Operations Research : An Introduction" – by H.A. Taha, PHI Pvt. Ltd., 6th edition
4. Linear Programming – by G. Hadley

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PROGRAMMABLE LOGIC CONTROLLERS
(ELECTIVE-IV)

Unit-I:

PLC Basics: PLC system, I/O modules and interfacing, CPU processor, programming Equipment, programming formats, construction of PLC ladder diagrams, Devices connected to I/O modules.

Unit-II:

PLC Programming: Input instructions, outputs, operational procedures, programming examples using contacts and coils. Drill press operation.

Unit-III:

Digital logic gates, programming in the Boolean algebra system, conversion examples
Ladder Diagrams for process control: Ladder diagrams & sequence listings, ladder diagram construction and flowchart for spray process system.

Unit-IV:

PLC Registers: Characteristics of Registers, module addressing, holding registers, Input Registers, Output Registers.

Unit-V:

PLC Functions: Timer functions & Industrial applications, counters, counter function industrial applications, Arithmetic functions, Number comparison functions, number conversion functions

Unit-VI:

Data Handling functions: SKIP, Master control Relay, Jump, Move, FIFO, FAL, ONS, CLR & Sweep functions and their applications

Unit-VII:

Bit Pattern and changing a bit shift register, sequence functions and applications, controlling of two-axis & three axis Robots with PLC, Matrix functions.

Unit-VIII:

Analog PLC operation: Analog modules& systems, Analog signal processing, Multi bit Data Processing, Analog output Application Examples, PID principles, position indicator with PID control, PID Modules, PID tuning, PID functions.

Text Books:

1. Programmable Logic Controllers- Principles and Applications by John W. Webb & Ronald A. Reiss, Fifth Edition, PHI
2. Programmable Logic Controllers- Programming Method and Applications –JR.Hackworth &F.D Hackworth Jr. –Pearson, 2004

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OBJECT ORIENTED PROGRAMMING
(ELECTIVE – IV)

Objectives:

1. To teach the student OOP principles using Java.
2. To teach the student to apply these principles in problem solving

UNIT-I:

Introduction: Creation of Java, importance of Java to internet, byte code, Java buzzwords, OOP Principles, Encapsulation, Inheritance and Polymorphism, data types, variables, declaring variables, dynamic initialization, scope and life time of variables, arrays, operators, control statements, type conversion and casting, compiling and running of simple Java program.

UNIT-II:

Classes and Objects: Concepts of classes and objects, class fundamentals Declaring objects, assigning object reference variables, introducing methods, constructors, usage of static with data and methods, usage of final with data, access control, this key word, garbage collection, overloading methods and constructors, parameter passing – call by value, recursion, nested classes and inner classes, exploring the String class.

UNIT-III:

Inheritance: Basic concepts, member access rules, usage of super key word, forms of inheritance, method overriding, abstract classes, dynamic method dispatch, using final with inheritance, the Object class.

UNIT-IV:

Packages and Interfaces: Defining, Creating and Accessing a Package, Understanding CLASSPATH, importing packages, differences between classes and interfaces, defining an interface, implementing interface, applying interfaces, variables in interface and extending interfaces.

UNIT-V:

Exception Handling and Multithreading: Concepts of Exception handling, types of exceptions, usage of try, catch, throw, throws and finally keywords, Built-in exceptions, creating own exception sub classes, Concepts of Multithreading, differences between process and thread, thread life cycle, creating multiple threads using Thread class, Runnable interface, Synchronization, thread priorities, inter thread communication, daemon threads, deadlocks, thread groups.

UNIT-VI:

Event Handling: Events, Event sources, Event classes, Event Listeners, Delegation event model, handling mouse and keyboard events, Adapter classes.

AWT: Concepts of components, container, panel, window, frame, canvas, Font class, Color class and Graphics.

UNIT-VII:

AWT Controls: Buttons, Labels, Text fields, Text area, Check boxes, Check box groups, Lists, Choice, Scrollbars, Menus, Layout Managers – Flow, Border, Grid, Card and Gridbag.

Swing – JApplet, JFrame and JComponent, Icons and Labels, Handling threading issues, text fields, buttons – The JButton class, Check boxes, Radio buttons, Combo boxes, Tabbed Panes, Scroll Panes, Trees, and Tables.

Applets – Concepts of Applets, differences between applets and applications, life cycle of an applet, types of applets, creating applets, passing parameters to applets.

UNIT-VIII:

Networking and Java Library: Basics of Networking, InetAddress, TCP/IP sockets, Datagrams, URL, URL connection, String handling, java.util, java.io and java.net packages.

TEXT BOOKS:

1. The Complete Reference Java J2SE 5th Edition, Herbert Schildt, TMH Publishing Company Ltd, NewDelhi./PHI
2. Big Java 2nd Edition, Cay Horstmann, John Wiley and Sons.

REFERENCE BOOKS:

1. Java How to Program, Sixth Edition, H.M.Dietel and P.J.Dietel, Pearson Education.
2. Core Java 2, Vol 1, Fundamentals, Cay.S.Horstmann and Gary Cornell, Seventh Edition, Pearson Education.
3. Core Java 2, Vol 2, Advanced Features, Cay.S.Horstmann and Gary Cornell, Seventh Edition, Pearson Education.
4. Beginning in Java 2, Iver Horton, Wrox Publications.

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**DATABASE MANAGEMENT SYSTEMS
(ELECTIVE-IV)**

Objective:

Learn about database design concepts, data models (Entity-Relationship and Relational Model), the database query language SQL and components of a database management system. Further topics include query processing and optimization techniques, transaction management, and storage and file structures

Syllabus:

UNIT – I:

Data base System Applications, data base System VS file System – View of Data – Data Abstraction – Instances and Schemas – data Models – the ER Model – Relational Model – Other Models – Database Languages – DDL – DML – database Access for applications Programs – data base Users and Administrator – Transaction Management – data base System Structure – Storage Manager – the Query Processor – History of Data base Systems. Data base design and ER diagrams – Beyond ER Design Entities, Attributes and Entity sets – Relationships and Relationship sets – Additional features of ER Model – Concept Design with the ER Model – Conceptual Design for Large enterprises.

UNIT – II:

Relational Model: Introduction to the Relational Model – Integrity Constraint Over relations – Enforcing Integrity constraints – Querying relational data – Logical data base Design – Introduction to Views – Destroying /altering Tables and Views.

Relational Algebra and Calculus: Relational Algebra – Selection and projection set operations – renaming – Joins – Division – Examples of Algebra overviews – Relational calculus – Tuple relational Calculus – Domain relational calculus – Expressive Power of Algebra and calculus.

UNIT – III:

Form of Basic SQL Query – Examples of Basic SQL Queries – Introduction to Nested Queries – Correlated Nested Queries Set – Comparison Operators – Aggregative Operators – NULL values – Comparison using Null values – Logical connectivity's – AND, OR and NOTR – Impact on SQL Constructs – Outer Joins – Disallowing NULL values – Complex Integrity Constraints in SQL 0 Triggers and Active Data bases.

UNIT – IV:

Schema refinement – Problems Caused by redundancy – Decompositions – Problem related to decomposition – reasoning about FDS – FIRST, SECOND, THIRD Normal forms – BCNF – Lossless join Decomposition – Dependency preserving Decomposition – Schema refinement in Data base Design – Multi valued Dependencies – forth Normal Form.

UNIT – V:

Overview of Transaction Management: ACID Properties – Transactions and Schedules – Concurrent Execution of transaction – Lock Based Concurrency Control – Performance Locking – Transaction Support in SQL – Introduction to Crash recovery.

UNIT – VI:

Concurrency Control: Serializability, and recoverability – Introduction to Lock Management – Lock Conversions – Dealing with Dead Locks – Specialized Locking Techniques – Concurrency without Locking.

Crash recovery: Introduction to ARIES – the Log – Other Recovery related Structures – the Write-Ahead Log Protocol – Check pointing – recovering from a System Crash – Media recovery – Other approaches and Interaction with Concurrency control.

UNIT – VII:

Overview of Storage and Indexing: Data on External Storage – File Organization and Indexing – Cluster Indexes, Primary and Secondary Indexes – Index data Structures – Hash Based Indexing – Tree base Indexing – Comparison of File Organizations – Indexes and Performance Tuning.

UNIT – VIII:

Storing data: Disks and Files: - The Memory Hierarchy – Redundant Arrays of Independent – Disks – Disk Space Management – Buffer Manager – Files of records – Page Formats – record formats.

Tree Structured Indexing: Intuitions for tree Indexes – Indexed Sequential Access Methods (ISAM) – B+ Trees: A Dynamic Index Structure.

Hash Based Indexing: Static Hashing – Extendable hashing – Linear Hashing – Extendable vs. Linear hashing.

Text Books:

1. Data base Management Systems, Raghurama Krishnan, Johannes Gehrke, TATA McGrawHill 3rd Edition
2. Data base System Concepts, Silberschatz, Korth, Mc.Graw hill, IV edition.

References:

1. Introduction to Database Systems, C.J.Date Pearson Education
2. Data base Systems design, Implementation, and Management, Rob & Coronel 5th Edition.Thomson
3. Data base Management System, Elmasri Navrate Pearson Education
4. Data base Management System Mathew Leon, Leon Vikas.
5. Data base Systems, Connoley Pearson education